

Evaluating Discrete Period Quadrature for Time-Frequency Analysis using Various Features of the Magnitude and Phase Spectra



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Background	Purpose of Study
<ul style="list-style-type: none">• Nystagmus: visual impairment characterized by involuntary, repetitive eye motion<ul style="list-style-type: none">• Perception of unstable visual field - <i>oscillopsia</i>• <i>StabilEyes</i>: mobile application to compensate for unwanted nystagmus eye motion<ul style="list-style-type: none">• “Shift” on-screen images at the correct frequency and phase in real time• Need efficient, accurate method of tracking frequency and phase of periodic eye motion	<ul style="list-style-type: none">• Evaluate the use of four spectral features produced by Discrete Period Quadrature (DPQ)<ol style="list-style-type: none">1. <i>Global maximum magnitude at signal period</i>2. <i>Local minimum magnitudes at subharmonics of signal period</i>3. <i>Global minimum variance of magnitude at signal period</i>4. <i>Global minimum RMS delta phase error at signal period</i>

Methods

- DPQ definition, for each period p and (discrete time) index n , for discrete signal $s[n]$:

$$Q[p, n] = \sum_{m=n}^{n-p+1} \frac{s[m] \left(\cos\left(\frac{2\pi(m-n)}{p}\right) + j \sin\left(\frac{2\pi(m-n)}{p}\right) \right)}{p}, 2 \leq p \leq P$$



- Signal period p_s inferred using one of the following features:

- Peak:

$|Q[p, n]|$ has global maximum at $p \cong p_s$

- Subharmonic:

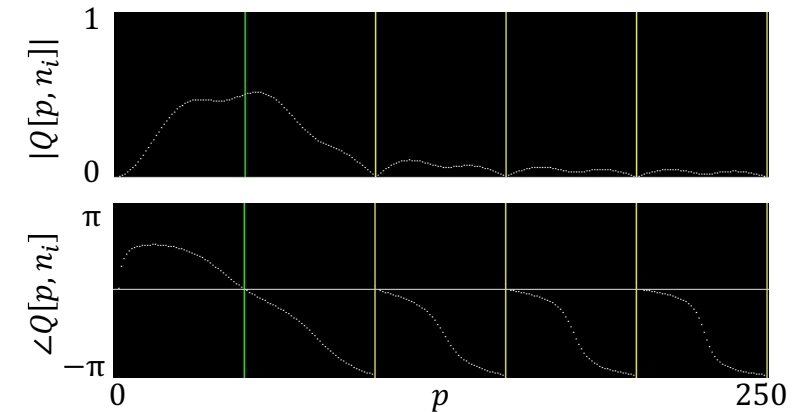
$|Q[p, n]|$ has local minima at $p \cong kp_s, k = 2, 3, 4, \dots$

- Variance:

$VAR(|Q[p, n]|)$ has local minima at $p \cong kp_s, k = 1, 2, 3, \dots$

- Delta Phase:

RMS error of $[\angle Q[p, n] - \angle Q[p, n - 1]] - \frac{2\pi}{p}$ has global minimum at $p \cong p_s$

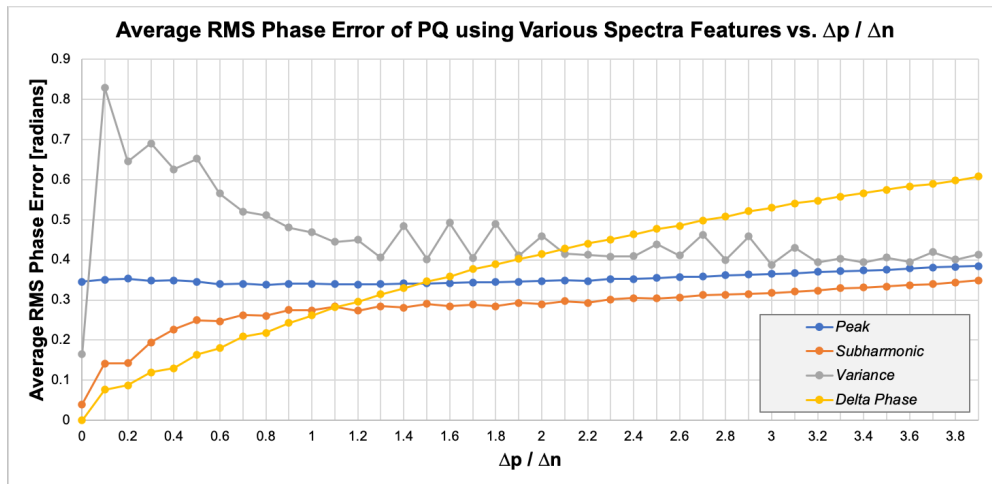


Magnitude and phase spectra at $p_s = 50$. The green and yellow lines denote p_s and its subharmonics.

- Experimental: using sinusoidal signal with **(1) changing signal period & (2) Gaussian Noise**
- Observational: real-time with interactive **non-sinusoidal waveform (sawtooth)**

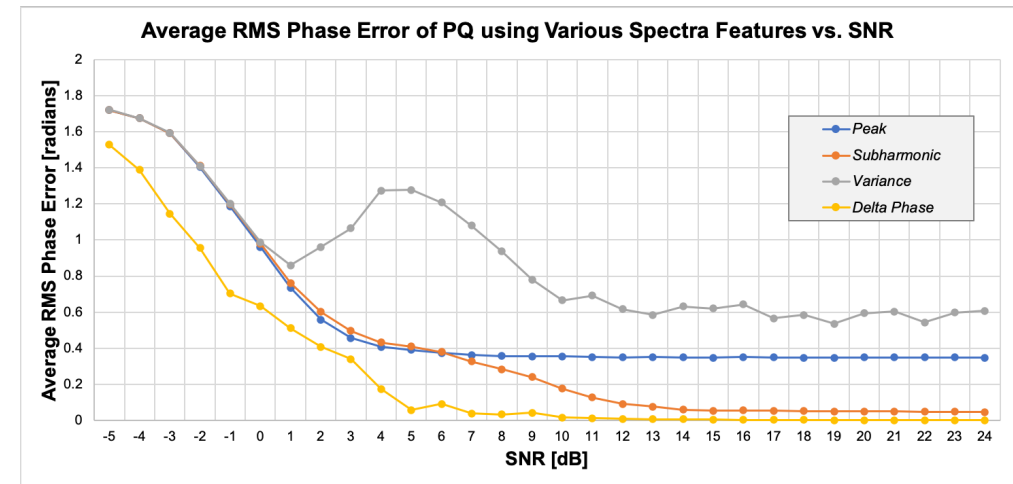
Results & Conclusions

Changing Signal Period ($\frac{\Delta p_s}{\Delta n}$)



Delta phase: smallest error between true signal and inferred phases until rate of change $\frac{\Delta p_s}{\Delta n} \approx 1$

Noisy Signal



Delta phase: smallest error between true signal and inferred phases for all SNRs tested

- Interactive testing with non-sinusoidal signals – delta phase performs best, most **consistently**
- Delta phase has some **memory** to aid in tracking, especially in the presence of noise
- Next step: analyze and characterize **DPQ** using **delta phase to infer period**